

Notes on Spivak's "Calculus on Manifolds"¹

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Theory

1-1 (1)

$$|x| = \sqrt{\sum_{i=1}^n x_i^2}.$$

$\sum_{i=1}^n x_i^2 = 0$ only if $x_i = 0$ for all x_i .

Therefore $|x| = 0$ only if $x = 0$.

1-2 (3)

$x \cdot x = \sum_{i=1}^n x_i^2 = |x|^2$. By (1-1) above,

$|x|^2 = 0$ only if $x = 0$, therefore $x \cdot x = 0$ only if $x = 0$.

(4)

By (3) above, $|x|^2 = x \cdot x$. We take the sqrt to get $|x| = \sqrt{x \cdot x}$.

Problems

1-1

$$x \cdot x \leq (\sum_{i=1}^n |x_i|)^2$$

$\sum_{i=1}^n x_i^2 \leq (\sum_{i=1}^n |x_i|)^2$ (with from i to n implied)

$\sum_{i=1}^n x_i^2 \leq \sum_{i=1}^n x_i^2 + C$, where C represents the extra factors as a result of multinomial expansion.

We obtain $C \geq 0$, which is true since all values $|x_i|$ in C are positive. ■

1-2

For equality to hold, $\sum_{i=1}^n x_i \cdot y_i = |x| \cdot |y|$.

This is *NOT* the same as Theorem 1-1(2), as the LHS may be negative. So equality holds when two conditions are satisfied:

(1) x and y are linearly dependent

(2) $\langle x, y \rangle$ is nonnegative. ■

1-3

Taking $?$ to stand for an unknown comparison:

$$|x-y|^2 = |x|^2 + |y|^2 + 2|x||y|$$

$$\sum_{i=1}^n (x_i - y_i)^2 = \sum_{i=1}^n x_i^2 + \sum_{i=1}^n y_i^2 + 2|x||y|,$$

$$\text{Expanding: } \sum_{i=1}^n (x_i - y_i)^2 = \sum_{i=1}^n x_i^2 + \sum_{i=1}^n y_i^2 - 2 \cdot \sum_{i=1}^n x_i y_i$$

$$\text{Canceling and simplifying: } -\langle x, y \rangle = |x||y|$$

By Theorem 1-1(2) it is clear that if $-\langle x, y \rangle \geq 0$,

$-\langle x, y \rangle \leq |x||y|$. In the opposite case, $-\langle x, y \rangle < 0$

and $|x||y| \geq 0$, so the comparison still holds. ■

1-4

$$||x| - |y|| = |\sqrt{\sum_{i=1}^n x_i^2} - \sqrt{\sum_{i=1}^n y_i^2}|$$

¹ I cannot guarantee the accuracy of every solution. If you spot a mistake, let me know @ ian.arawjo - at - gmail - dot - com.

$$|x-y| = \sqrt{\sum x_i^2 + \sum y_i^2 - 2 \cdot \sum x_i y_i}$$

$$|x-y|^2 = |x|^2 + |y|^2 - 2\langle x, y \rangle$$

$$||x| - |y||^2 = |x|^2 + |y|^2 - 2|x||y|$$
 We're comparing: $||x| - |y||^2 \stackrel{?}{=} |x-y|^2$,
 therefore $|x||y| \stackrel{?}{=} \langle x, y \rangle$ (NOTE the sign reversal!)
 By Theorem 1-1(2), we know that $|x||y| \geq |\langle x, y \rangle|$,
 making $\stackrel{?}{=}$ equal to \leq . Similarly, if $\langle x, y \rangle$ is less than
 0, then the comparison still holds.
 Therefore $||x| - |y|| \leq |x-y|$. ■

1-5

First, shift the axes so that $x = 0$ (origin). Then:

$|z| \stackrel{?}{=} |z-y| + |y|$ i.e.
 $|z| - |y| \stackrel{?}{=} |z-y|$ i.e. (choose $|z|$ to be $\geq |y|$)
 $|z|^2 + |y|^2 - 2|z||y| \stackrel{?}{=} |z^2| + |y^2| - 2\langle z, y \rangle$
 $|z||y| \stackrel{?}{=} \langle z, y \rangle$ (same as 1-4 above)
 Therefore $\stackrel{?}{=}$ equals \leq by Theorem 1-1(2). ■

Geometric interpretation:

Here it is assumed that no two points are equal.
 The points z, y, x form a triangle in R^n , $n \geq 2$.
 By connecting points, we obtain side lengths $|z-x|$, $|z-y|$,
 and $|y-x|$. The proved inequality states that no
 side can be greater than the other two sides combined.

1-6

$\int_a^b f(x) \Delta x$ as step
 $\Delta x \rightarrow 0$. Hence:
 $\int_a^b fg = \sum_{x=a}^b \{f(x)g(x) \Delta x\}$
 $(\int_a^b f^2)^{1/2} = \sqrt{\sum_{x=a}^b \{f(x)f(x) \Delta x\}}$
 $(\int_a^b g^2)^{1/2} = \sqrt{\sum_{x=a}^b \{g(x)g(x) \Delta x\}}$
 If F and G stand for the infinite sums, then loosely speaking,
 $|\langle F, G \rangle| \leq |F||G|$ by Theorem 1-1(2).
 (b)(c) omitted

1-7

(a) $|T(x)| = \sqrt{\langle T(x), T(x) \rangle}$. We take T to be inner product
 preserving, so that $\langle T(x), T(x) \rangle = \langle x, x \rangle$; then
 $\sqrt{\langle x, x \rangle} = |x|$. (inner product \rightarrow norm preserving)
 Proving the converse:

$$\langle Tx, Ty \rangle = (|Tx + Ty|^2 - |Tx - Ty|^2) / 4$$

$$= (|T(x+y)|^2 - |T(x-y)|^2) / 4$$

We take T to be norm preserving, so:

$$\langle Tx, Ty \rangle = (|x+y|^2 - |x-y|^2) / 4 = \langle x, y \rangle. \blacksquare$$

(b) Say T was not 1-1. Then it could be that
 $|T(x)| = |x|$ and $|T(a)| = |a|$, for some $a \neq x$,
 s.t. $T(x) = T(a)$. It is certainly possible that a and x
 are different vectors that give the same norm; consider
 $x = (1,0)$ and $a = (0,1)$ where $T(x) = T(a) = (1,0)$. However,
 it is clear in that case that $\langle Tx, Ta \rangle \neq \langle x, a \rangle$. Generalizing,
 we have $\langle Tx, Tx \rangle = \langle x, a \rangle$ (since $Ta = Tx$), where $a \neq x$,
 which violates inner product preservation. ■

(Since T is a bijection, it must have an inverse.)

1-10

(omitted)

1-11

First: $\langle (x,z), (y,w) \rangle = \sum x_i * y_i + \sum z_i * w_i = \langle x,y \rangle + \langle z,w \rangle$. (We could split the dot product since x and y , z and w are of the same length.)

Second: $|(x,z)| = \sqrt{\sum x_i^2 + \sum z_i^2} = \sqrt{|x|^2 + |z|^2}$. ■

1-12

(omitted)

1-13

If $\langle x,y \rangle = 0$, we have that $|x+y|^2 - |x-y|^2 = 0$ by polarization. Then $|x+y|^2 = \sum (x_i - y_i)^2 = |x|^2 + |y|^2$ (since $2\langle x,y \rangle = 0$). ■

Subsets of Euclidean Space

Proof

By definition, a subset C of \mathbb{R}^n is closed if $\mathbb{R}^n - C$ is open. Take a closed rectangle C in \mathbb{R}^n , where $C = [a_1, b_1] \times \dots \times [a_n, b_n]$ and $a_i < b_i$ by convention. Now $\mathbb{R}^n - C = ((-\infty, a_1) \cup (b_1, \infty)) \times \dots \times ((-\infty, a_n) \cup (b_n, \infty))$.

Since \mathbb{R}^n is composed of open intervals (open), C is closed. ■

Note on the definition of compactness:

“A set G is compact if every open cover C of the set contains a finite subcover U .”

When I first read that statement, I was very confused. I thought: “Say $G = (0, 1)$. Taking $C = \{G\}$, $U = C$, we have a finite subcover (one element) and so G is compact. (???)”

The key word in the definition is **every**. It's perhaps clearer if we invert it:

“A set G is noncompact if there exists an open cover C which contains only infinite subcovers.”

Example: $G = (0,1)$, $C = \{(1/n, 1-1/n) \mid n > 1\}$. C is infinite. Since C approaches $(0,1)$ in the limit of $n \rightarrow +\infty$, effectively ‘widening’, no finite set will cover G , and thus we've proven that G is noncompact.

Alternative example: $G = [0,1]$, $C = \{(-1+a, a) \mid a \in (0, 2)\}$. C is an infinite cover, yet $(-0.01, 0.99) \cup (0.01, 1.01)$ covers G . This is evidence toward G being compact, but we'd have to

prove that there cannot exist an open cover with only infinite subcovers.

In plain english: to prove G is noncompact, find an open cover which approaches the boundary of G in its limit.

Problems

1-14

For every element x of an open set O in Euclidean space, there is an open rectangle A that contains x . Say we have open sets O_1 and O_2 , with corresponding open rectangles A_1 and A_2 . $A_1 \cup A_2$ is therefore a subset of the union $O_1 \cup O_2$, meaning that for each element x of $O_1 \cup O_2$, x is a member of A_1 , A_2 , or both. By definition, this makes $O_1 \cup O_2$ an open set. ■

Similarly, take the union of any number of open sets $U = \bigcup_{i=1}^n O_i$, where n can stand for ∞ . Then each O_i has an open rectangle A_i , and for each element x of U , $x \in A_i$ for some i . ■

For intersection of two open sets $U = O_a \cap O_b$, we have $A = A_a \cap A_b$ where for all $x \in U$, $x \in A$ and where each A_z contains all open rectangles of O_z . We must prove that the intersection of an open rectangle is open:

Choose any two rectangles from both A_a and A_b :

$A_1 = (a_{11}, b_{11}) \times \dots \times (a_{1n}, b_{1n})$ and $A_2 = (a_{21}, b_{21}) \times \dots \times (a_{2m}, b_{2m})$ for some $n, m \geq 1$. Now for each dimension (a, b) in A_i there are three possibilities:

- (1) $m > n$ or $n > m$, so we drop the dimension;
- (1) Either (a_{1i}, b_{1i}) and (a_{2i}, b_{2i}) are mutually exclusive, or
- (2) intersect, in which case there is an open rectangle (a_{2i}, b_{1i}) that covers the intersection (we can choose the order of indices such that this is true).

Thus the intersection of two A_i 's forms a new open rectangle where, freely choosing $n \leq m$,

$$A_j = (a_{21}, b_{11}) \times \dots \times (a_{2n}, b_{1n})$$

and if any dimension is the null set $\{\}$ (an open set), $A_j = \{\}$.

From this, $A_a \cap A_b$ can be reconstructed as the union of the intersection of all open rectangles between them. Thus for every element x in U , x is a member of an open rectangle in A . ■

On the contrary, infinitely many open sets can converge to a number. Consider a set which "shrinks" in its limit, converging to a value smaller than its starting value. For instance, $O = \{(1/n, 2+1/n) \mid n \in \mathbb{Z}^+\}$ converges to the interval $[0, 2]$ as n

goes to infinity. Intersection of all O 's elements yields $[0, 2]$, a closed set. ■

1-15

Taking $r = 0$ yields the null set $\{\}$. If $r > 0$, then by the properties of the real numbers, there exists an $0 \leq x < r$. Take $a = 0$ to maximize x . Now x equals plus or minus $r - \epsilon$ for some ϵ approaching zero. Thus for the given r we have $(-r, r)$, an open set. Since the union of infinite open sets is open (1-14), $\{x \in \mathbb{R}^n : |x - a| < r\}$ is open. ■

1-16

(i) interior: $|x| < 1$, exterior: $|x| > 1$, boundary: $|x| = 1$.
(ii) interior: $\{\}$, exterior: $|x| \neq 1$, boundary: $|x| = 1$.
(iii) interior: $\{\}$, exterior: at least one x_i is irrational, boundary: each x_i is rational

1-17

$A = \{\text{point}(x, x) \mid 0 < x < 1\}$ (i.e. an open diagonal line)
* I think this is what the question is asking for?

1-18

$A = \{(a_i, b_i) \mid 0 < a < b < 1 \text{ and rational } r \in (a_i, b_i)\}$.
It is obvious that this union results in the open set $(0, 1)$.
Therefore the boundary of A must be the limits 0 and 1, i.e. $[0, 1] - A$.

1-19

0 and 1 are rational. We must show that there are no 'gaps' containing only irrational numbers in the interval $(0, 1)$. Suppose such an interval $[a, b]$ existed, where $0 < a < b < 1$ and a, b are irrational. By the density of the reals, there exists a rational number $a < r < b$. So the interval $[a, b]$ cannot exist, and $[0, 1]$ must be contained in A . ■

1-20

$U \subset \mathbb{R}^n$ and U is compact, meaning that every open cover \mathcal{O} of U contains a finite subcover A . Say U was open ($v \neq w$). For each $U_i = (v, w)$ in U , we can form an infinite cover:

$$\mathcal{O} = \{(v + (v+w)/n, w - (v+w)/n) \mid n \geq 2\}$$

which approaches (v, w) in the limit $n \rightarrow \infty$. Therefore U cannot be open. Moreover, U is bounded by $\cup_i \{v_i, w_i\}$.

By Corollary 1-6, $X \subset \mathbb{R}^n$ is compact if each $X_i \subset \mathbb{R}^n$ is. By the above reasoning, if X_i is compact, X_i is closed and bounded. Therefore X is closed and bounded. ■

1-21

(a) Suppose there isn't such a number. Then $|y - x| = 0$. For that to be true, $x = y$. But if $x = y \in A$ then $x \in A$, a contradiction.

(b) (c) omitted

1-22

If $C \in \mathbb{R}^n$ is a compact subset of the open set U , then C is closed and bounded (Problem 1-20). Thus $U - C$ is open and cannot be empty. Create the set Y as follows: For each c on the boundary of C , construct an open rectangle within U (this is

possible as U is open). Then $D = C + Y + \text{boundary}(Y)$, and $C \subset D^\circ$, $D \subset U$. ■

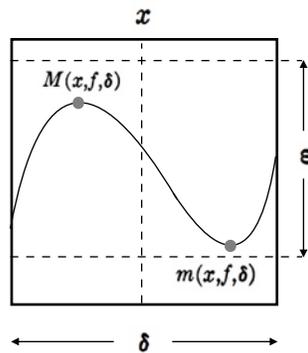
Functions and Continuity

Note on Theorem 1-11 (Proof)

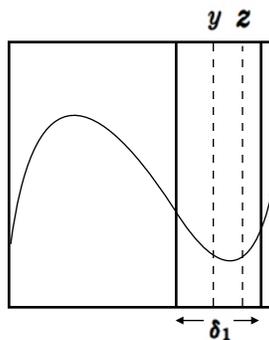
Spivak's notation can become a bit cumbersome, so here's a visual description of the two cases.

The first case is trivial: imagine removing a bounded rectangle from \mathbb{R}^n . The resulting space would be open.

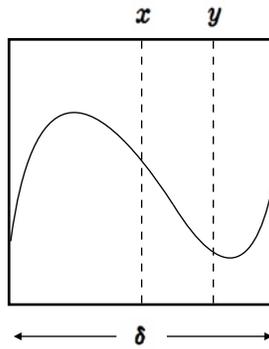
The second case appears tricky. Keep in mind the fact that $M(\dots) - m(\dots)$ stands for (roughly) the maximum value - minimum value of the function inside a given interval. If we visualize this interval as a square,



consider a value y such that $|x - y| < \delta$:



In other words, y is 'inside the square.' Now since the total interval is open (we've established this with $M(\dots) - m(\dots) < \epsilon$), we can find an even smaller interval:



Since $M(\dots) - m(\dots)$ inside this smaller interval is less than ϵ , $\rho(y, f) < \epsilon$, proving $C \subset \mathbb{R}^n - B$.

Problems

* Diversion into Spivak's Calculus *

Why the diversion? Well, it's been awhile since I learned Calc I. Like most people, I memorized the derivative / integral identities and virtually forgot about how to derive the fundamental theorem of calculus. Coming from the side of open balls in \mathbb{R}^n , I see now how intertwined the concept of a limit is with the boundary of an open interval. But to know I am answering these problems satisfactorily, we must go off on a tangent into Spivak's "Calculus," chapters 5 and 6. (I promise that this tangent will reveal its further use shortly!)

Chapter 5: Limits

Definition: The function f approaches the limit L near a if for every $\epsilon > 0$ there is some $\delta > 0$ such that, for all x , if $0 < |x - a| < \delta$, then $|f(x) - L| < \epsilon$.

("This definition is so important, everything we do from now on depends on it." (p. 79))

Properties: $\lim fg = \lim f * \lim g$
 $\lim (f+g) = \lim f + \lim g$
 $\lim 1/g = 1/(\lim g)$ as long as $g \neq 0$

Chapter 6: Continuity

Definition: The function f is 'continuous at a ' if the limit of $f(x)$ as x approaches a equals $f(a)$.

In other words if f is everywhere continuous, then any limit of f at a can be replaced by $f(a)$.

Properties: If f, g are continuous at a , then:
 $f + g$ is continuous at a
 fg is continuous at a

if $g(a) \neq 0$, $1/g$ is continuous at a

Composition: If g is continuous at a and f is continuous at $g(a)$, then $f(g(x))$ is continuous at a .

Now we are ready to tackle continuity problems with some clarity behind our assumptions.

1-23

A) If $\lim f(x) = b$ (as x approaches a), show that $\lim f^i(x) = b^i$ for i from 1..m.

By definition on p. 11, $f(x) = (f^1(x), \dots, f^m(x))$.

$$\begin{aligned} \lim f(x) &= \lim (f^1(x), \dots, f^m(x)) = (b_1, \dots, b_m) \\ &= \lim ((f_1(x), \dots, 0) + \dots + (0, \dots, f^m(x))) \\ &= \lim (f_1(x), \dots, 0) + \dots + \lim (0, \dots, f^m(x)) \text{ (prop)} \end{aligned}$$

which means for each i ,
 $\lim (\dots f_i(x) \dots) = (\dots b_i \dots)$
since $\lim 0 = 0$. ■

B) omitted (the derivation is similar)

1-24

A) $\lim f(x) = \lim (f_1(x), \dots, 0) + \dots + \lim (0, \dots, f^m(x))$
which means for each i ,
 $\lim (\dots f_i(x) \dots) = (\dots f(a) \dots)$
for f to be continuous at a . ■

B) omitted

1-25

If a function h is continuous, then $T(h)$ is a linear combination of h_i 's. By the additivity and homogeneity properties of limits, $T(h)$ must also be continuous (see 1-24).

1-26

(a) A straight line can be defined by the set of points (x, ax) .
Let $C = \mathbb{R}^2 - A =$

$\{(x,y) \in \mathbb{R}^n : x \leq 0 \text{ and } (y \leq 0 \text{ or } y \geq x^2)\}$

Now for each line $\{(x, ax)\}$, if a or x is ≤ 0 , the point is in C . For $(x, ax) > (0,0)$, we must show that $ax > x^2$ over some interval $(0, d)$. This is the same as saying $x < a$. Since $a > 0$, we can find an x such that $0 < x < a$. Taking $d=a$ completes the proof. ■

(b) omitted

1-27

**(to do: prove f is continuous)

If $f(x)$ is continuous then the limit as $x \rightarrow a$ is $f(a) = 0$.
Pick some $e \in \mathbb{R}^n$, $r > |e| > 0$, and produce $x = (a + e)$. Now $f(a+e) = |e|$. Form a new vector $d \in \mathbb{R}^n$ such that $r > |d| > |e|$ (property of the real numbers). Now $f(a+e+d) = |d+e| < r$. Since we can do this ad infinitum, there must exist an open interval bounded by magnitude r .

Chapter 2: Differentiation

Note on Theorem 2-3

Spivak uses the notation $Df(a) = f$ here, which considerably confused me. The terseness of the statement is not strictly justified; it would, in my opinion, be much clearer if Spivak used Δx or h .

The source of the confusion stems from $Df(a)$'s definition on page 17, where Spivak uses the same variables x, y to mean two different things:

“For the moment let us consider the function $f: \mathbb{R}^2 \rightarrow \mathbb{R}$ defined by $f(x, y) = \sin x$. Then $Df(a, b) = \lambda$ satisfies $\lambda(x, y) = (\cos a)x$.”

Since he's defining the function, technically Spivak can choose whichever free variables he wishes; however it would help considerably if the chosen variables were consistent with their contextual meanings, e.g. $\lambda(h, k)$.

Note that $Df(a) = f$ doesn't mean the derivative itself is $f(a)$ (at least in the classic sense), but $f(\Delta x)$.